

Magnetic effect of current

① Biot-Savart law

| | |
|---|---|
| $d\vec{B} = \frac{\mu_0}{4\pi} I \frac{d\vec{l} \times \vec{r}}{r^3}$ | $dB = \frac{\mu_0}{4\pi} \frac{I \cdot dl \cdot \sin\theta}{r^2}$ |
|---|---|

$\mu_0/4\pi = 10^{-7}$

② Formulae of field for wire

| |
|---|
| $B = \frac{\mu_0 I}{4\pi r} (\sin\alpha + \sin\beta)$ |
|---|

③ $\log_e 2 = 1 - \frac{1}{2} + \frac{1}{3} - \frac{1}{4} + \frac{1}{5} - \dots$

④ m.f.d for polygon of n sides

| |
|--|
| $B_{\text{centre}} = \frac{\mu_0 n I}{4\pi r} \sin(\pi/n) \cdot \tan(\pi/n)$ |
|--|

total sides π \rightarrow side length.

⑤ Neutral point (for two parallel wires)

| | |
|---------------|----------------------------|
| $x = I_1 r$ | near small magnitude of I. |
| $(I_1 + I_2)$ | |

for 2 \perp r wires

| | |
|-----------------------------|--|
| Neutral point \rightarrow | $y = \left(\frac{I_1}{I_2}\right) x$ |
| | $B_p = \frac{\mu_0}{2\pi d} (x^2 + y^2)^{1/2}$ |

⑥ Field at centre of arc

| |
|---|
| $B_c = \frac{\mu_0 I}{4\pi R} (\theta)$ |
|---|

- point lies at axial of wire contributes zero magnetic field.

⑦ field at the centre of symmetrically located disc.

$I_1 R_1 = I_2 R_2 \Rightarrow I_1 \theta_1 = I_2 \theta_2$

| |
|---|
| $\frac{I_1}{A} \theta_1 = \frac{I_2}{A} \theta_2$ |
|---|

Field at the axis of ring

(current carrying coil)

① $B_{\text{axis}} = \frac{\mu_0}{4\pi} \frac{2\pi n^2 I x}{(R^2 + x^2)^{3/2}}$

$n = I \times A = I \times \pi R^2$

field at axis of solenoid

② $B_{\text{centre}} = \frac{\mu_0 I}{4\pi R} 2\pi \Rightarrow \frac{\mu_0 I}{2R}$

$\rightarrow B_{\text{axis}} = \frac{B_{\text{centre}}}{\left(1 + \frac{x^2}{R^2}\right)^{3/2}}$

Hollow pipe

$B_s = \frac{\mu_0 I}{4\pi 2R}$

① $B_{\text{out}} = \frac{\mu_0 2I}{4\pi r}$

$B_{\text{in}} = 0$

$B_{\text{out}} \propto \frac{1}{r}$

② on the surface ($r=R$) $\Rightarrow \frac{\mu_0 2I}{4\pi R}$

③ Inside ($r < R$)

$B_{\text{inside}} = 0, I_{\text{enc}} = 0$

solid pipe i. thick pipe

① $B_{\text{out}} = \frac{\mu_0 2I}{4\pi r}$

$B_{\text{out}} = B_s \times R/r$

② on the surface ($r=R$)

$B_s = \frac{\mu_0 2I}{4\pi R}$

$B_{\text{out}} \propto \frac{1}{r}$

③ $B_{\text{inside}} = \frac{B_s \times r}{R}$

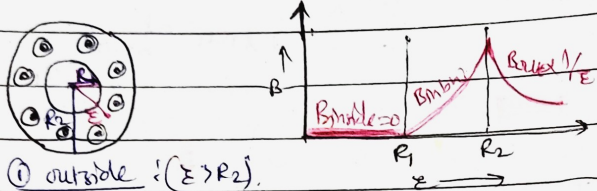
class theorem = Ampere's law
 Biot-Savart's law = Coulomb's law

⑧ Ampere's law

$$\int \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$

$$B \cdot dl \cos 0 = \mu_0 I_{enc}$$

* Annular pipe



① outside ($z > R_2$)

$$B_{out} = \frac{\mu_0 2I}{4\pi z}$$

② $B_{in} = \frac{\mu_0 2I}{4\pi \epsilon} \left(\frac{\epsilon^2 - R_2^2}{R_2^2 - R_1^2} \right)$ → partial Area
 → total Area

③ $B_{in} = \epsilon < R_1 \Rightarrow 0$ → imp

⑪ spiral

$$B = \frac{\mu_0 NI}{2(b-a)} \log\left(\frac{b}{a}\right)$$

CH-2 motion of charged particle in μ_0 field

① $\vec{F}_{in} = q(\vec{v} \times \vec{B})$

a) circular path $\theta = 90^\circ (\vec{v} \perp \vec{B})$

$$F_{max} = qvB$$

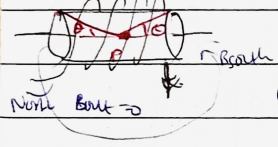
→ $\epsilon = mV$ $\Rightarrow \sqrt{2mK}$ $\Rightarrow \sqrt{2mqV}$
 qB qB qB

IF $k_i \neq 0$

$$\epsilon = \frac{\sqrt{2mqV + k_i}}{qB}$$

Solenoid & Toroid

① Solenoid



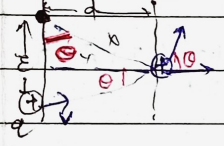
① $B_{centre} = \mu_0 NI$ $\theta_1 = \theta_2 = 0$

② $B_{in} = \frac{1}{2} \mu_0 NI$ $\Rightarrow n = \frac{N}{l}$

→ $T = \frac{2\pi m}{qB}$

i) Deviation in circular region

Case-i) $d < \epsilon$



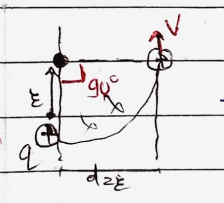
$\sin \theta = d/\epsilon$

$t = \frac{d}{v} = \frac{d}{qB}$

ii) at general point θ

$$B = \frac{1}{2} \mu_0 NI (\cos \theta_1 + \cos \theta_2)$$

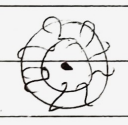
Case ii) $d = \epsilon$



$\theta = \frac{\pi}{2}$

time = $\frac{\pi m}{2qB}$

② Toroid



$B_{in} = \frac{\mu_0 NI}{2\pi r}$

$n = \frac{N}{l}$
 mean circumference length

Direction and $B_{out} = 0$

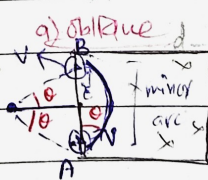
③ Field due to thin sheet of ∞ length & width

$$B = \frac{1}{2} \mu_0 J$$

$J = I/A = I/2r\epsilon$

current density

Case iii) $d > \epsilon$



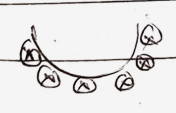
deviation = 2θ

time = $\frac{2\theta m}{qB}$

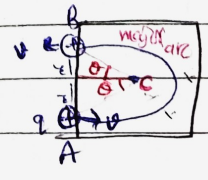
$AB = 2\epsilon \sin \theta$

④ Field at the axis of cylinder having

semicircular cross-section



$$B = \frac{1}{\pi} \mu_0 J$$



→ deviation = $2\pi - 2\theta$

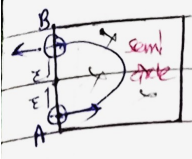
→ time = $\frac{(2\pi - 2\theta) m}{qB}$

→ $AB = 2\epsilon \sin \theta$

$$B_{ax1} = \frac{2\mu_0 M x}{4\pi (a^2 + x^2)^{3/2}} \Rightarrow B_{ax2} = \frac{2\mu_0 M}{4\pi x^3}$$

$$B_{equator} = \frac{\mu_0 M}{4\pi (x^2 + a^2)^{3/2}} \Rightarrow B_{eq} = \frac{\mu_0 M}{4\pi x^3}$$

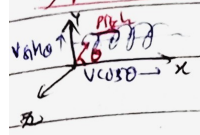
$$AB = 2a$$



deviation = π

$$\text{time} = \frac{\pi m}{qB}$$

b) Helical path



① Radius = $\frac{mv_{\perp}}{qB}$

② Time pd. = $\frac{2\pi m}{qB}$

③ Pitch = speed \times time
 $v_{\parallel} \times T$

cyclotron

① Total work done

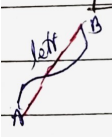
$$NqEd = K_{max}$$

(2 times work is done by e.f. at entry and leaving side)

② $R = \frac{\sqrt{2mK}}{qB}$ $K_{max} = \frac{q^2 B^2 R^2}{2m}$

② Force on current carrying conductor:

$$d\vec{F} = I(d\vec{l} \times \vec{B})$$



$$F = I(l \sin \theta) B$$

③ Force b/w 11el & 1er wires.

11el wires

$$F_1 = F_2 = \frac{\mu_0 2 I_1 I_2 \times l}{4\pi r}$$

Force/length = $\frac{\mu_0 2 I_1 I_2}{4\pi r}$

1er wires

$$F = \frac{\mu_0 2 I_1 I_2 \log_e \left[\frac{d+l}{d} \right]}{4\pi}$$

④ motion of charged particle in M. & E. field.

$$F = q[\vec{E} + (\vec{v} \times \vec{B})]$$

when $B \perp v \perp E$: $\vec{E} = \vec{B} \times \vec{v}$

⑤ moving coil galvanometer

$$NIBA = C\phi$$

a) current sensitivity $\Rightarrow \frac{\phi}{I} = \frac{NAB}{C}$

C = torsional const. / spring const

ϕ = angle of devⁿ / deflection

b) Voltage sensitivity $\Rightarrow \frac{\phi}{V} = \frac{NAB}{Rc}$ $\frac{\text{Sens current}}{R}$

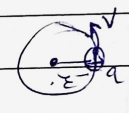
Moving charges & Magnetism

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{q(\vec{v} \times \vec{r})}{r^3} \quad B = \frac{\mu_0 qv \sin \theta}{4\pi r^2}$$

a) Revolving sphere.

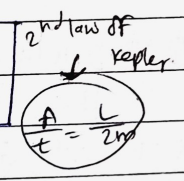
$$B = \frac{\mu_0 qv}{4\pi r^2}$$

$$B = \frac{\mu_0 q\omega}{4\pi r}$$



b) orbital motion of e⁻

$$B = \frac{\mu_0 ev}{4\pi r^2} \text{ or } \frac{\mu_0 e\omega}{4\pi r}$$



* magnetic dipole moment of revolving charge.

| | | | |
|---|---|----|-----------------------------|
| M | = | q | called gyromagnetic ratio |
| L | = | 2m | value for e ⁻ is |
| | | | 8.8×10^{10} c/kg |

⑥ Bohr's magneton

$$\mu = \frac{eh}{4\pi m} \Rightarrow \text{for } e^- \Rightarrow 9.27 \times 10^{-24} \text{ Am}^2$$

$m = NIA \rightarrow$ closed body

$m = \frac{qL}{2m} \rightarrow$ point charge

$L = I\omega$

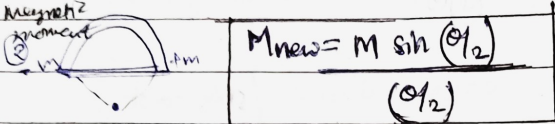
$M = m \times l_p \rightarrow$ bar magnet
 magnetic moment \rightarrow pole strength

*** Force b/w moving charges.**

| | |
|--|------------------------------------|
| $F_m = \frac{\mu_0}{4\pi} \frac{q_1 q_2}{r^2} v_1 v_2$ | $\mu_0 \epsilon_0 = \frac{1}{c^2}$ |
|--|------------------------------------|

Bar magnet.

① $M = m \times l_p$ (pole strength) $[Am^2]$
 $Am \times m$



*** Earth magnetism ***

① $\alpha =$ angle of declination

α at centre of earth is 11.5°

② $\tan \delta = \frac{B_V}{B_H}$ $B_E = \sqrt{B_V^2 + B_H^2}$

③ Relⁿ b/w false angle of dip & true angle of dip.

$\tan \delta' = \frac{\tan \delta}{\cos \theta}$

$\theta =$ angle b/w meridian & plane other than m. meridian

$\delta' =$ inclination of needle in plane other than m. meridian

$\delta =$ inclination of angle in magnetic meridian

(4) Tangent law

$B_{ext} = B_H \tan \theta$

(5) Tangent Galvanometer.

$\frac{\mu_0 N I}{2R} = B_H \tan \theta$

(6) vibration magnetometer

$T = 2\pi \sqrt{\frac{I}{MB_H}}$

$T_1 = T/n$
 $M_1 = M/n$

$I = \frac{I}{n^3}$

| | |
|---------------|-------------------|
| M_1 (large) | $= T_d^2 + T_s^2$ |
| M_2 (small) | $T_d^2 + T_s^2$ |

T_s center time period

magnetic field $\Rightarrow B \Rightarrow \mu = \frac{B}{\mu_{med}}$

magnetising $(H) = \frac{B}{\mu_0}$

magnetic properties

$\sqrt{2} = 1.414$

(1) Permeability

Relative permeability $(\mu_r) = \frac{\mu_{med}}{\mu_0}$

(2) Intensity of magnetising field (H) or magnetising field

$\vec{H} = \frac{\vec{B}_{ext}}{\mu_0}$

$B = \mu_r B_0$
 $(B \propto \mu)$

(3) Intensity of magnetisation (I)

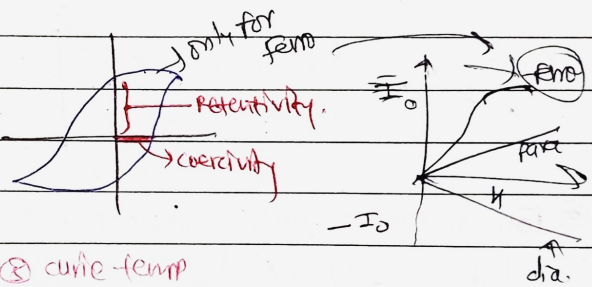
$\vec{I} = \frac{\vec{B}_M}{\mu_0} - \frac{\vec{B}_{ind}}{\mu_0} = \frac{M}{A} = \frac{M}{V}$

only magnetic moment $(M = \vec{m}N)$

(4) magnetic susceptibility (χ_m)

$\chi_m = \frac{I}{H} = \frac{B_{ind}}{B_{ext}}$

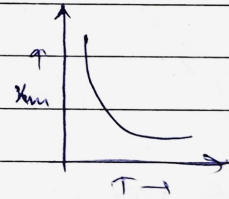
diff. moment pole strength



(5) Curie temp

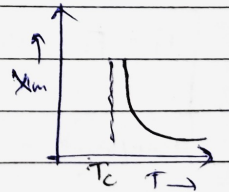
for Paramagnetic,

$\chi_m = \frac{c}{T}$

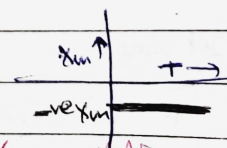


for ferro.

$\chi_m = \frac{c}{(T - T_c)}$



for dia,



Relⁿ b/w permeability & susceptibility

$\mu_r = 1 + \chi_m$